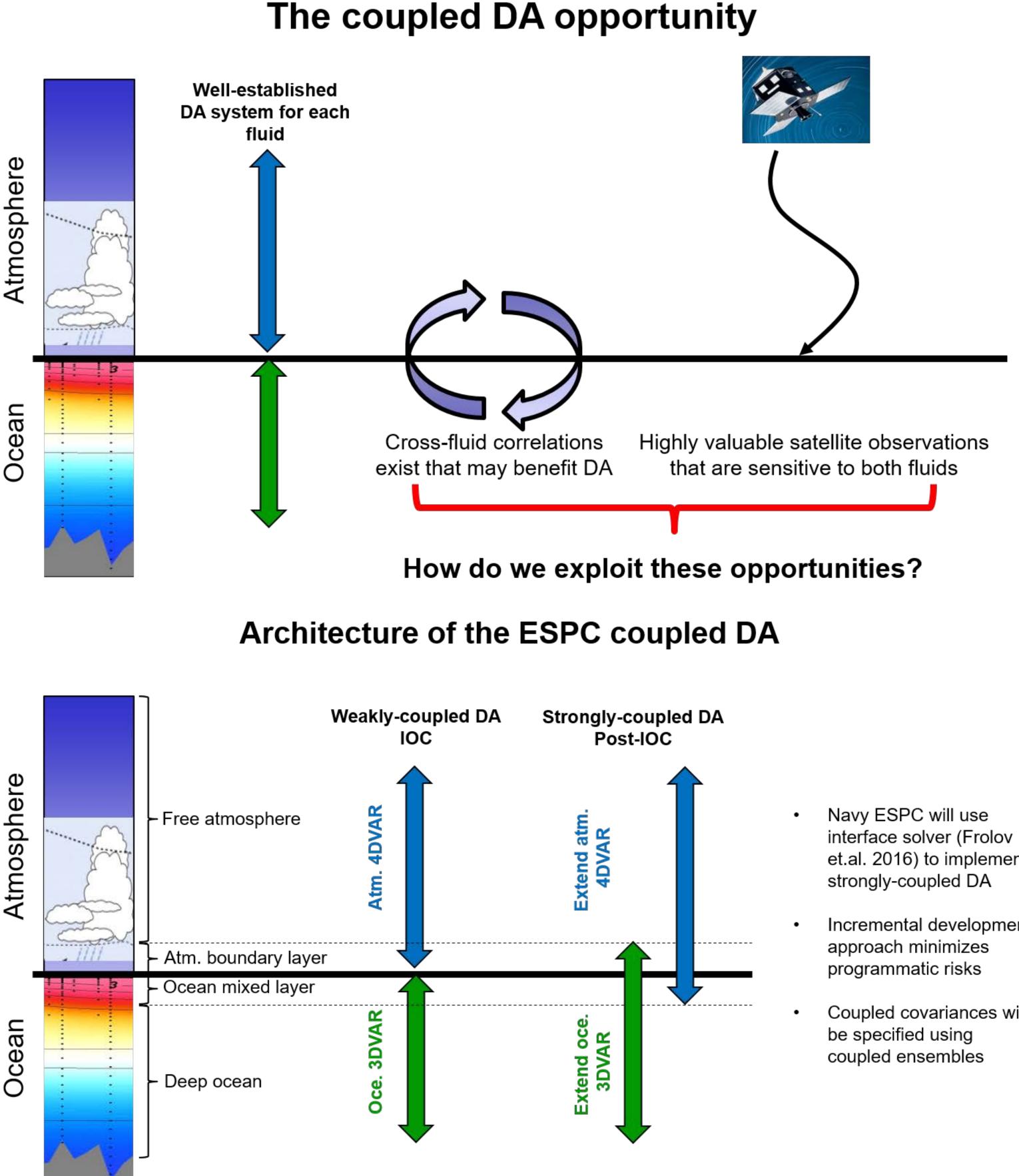
U.S. NAVAL RESEARCH LABORATORY

Abstract

Data assimilation under global coupled Earth System Prediction Capability (ESPC) presents significantly greater challenges than data assimilation in forecast models of a single earth system like the ocean and atmosphere. In forecasts of a single component, data assimilation has broad flexibility in adjusting boundary conditions to reduce forecast errors; coupled ESPC requires consistent simultaneous adjustment of multiple components within the earth system: air, ocean, ice, and others. Data assimilation uses error covariances to express how to consistently adjust model conditions in response to differences between forecasts and observations; in coupled ESPC, these covariances must extend from air to ice to ocean such that changes within one fluid are appropriately balanced with corresponding adjustments in the other components. We show several algorithmic solutions that allow us to resolve these challenges. Specifically, we introduce the interface solver method that augments existing stand-alone systems for ocean and atmosphere by allowing them to be influenced by relevant measurements from the coupled fluid. Plans are outlined for implementing coupled data assimilation within ESPC for the Navy's global coupled model. Preliminary results show the impact of assimilating SST-sensitive radiances in the atmospheric model and first results of hybrid DA in 1/12 degree model of the global ocean.



Milestones

- 1) Implement hybrid covariance in existing solvers ATM: NAVDAS-AR-Hybrid in operations since fall 2016 OCE: NCODA-Hybrid in development
- 2) Implement hybrid coupled state variables ATM: SST, ice concentrations velocities and temperatures, ... OCE: scatterometer winds, radiative flux retrievals, ice
- 3) Coupled covariance Use perturbed observation method Leverage work on global coupled ensembles
- 4) Test benefits of the coupled DA ATM: initial testing is underway OCE: yet to be done

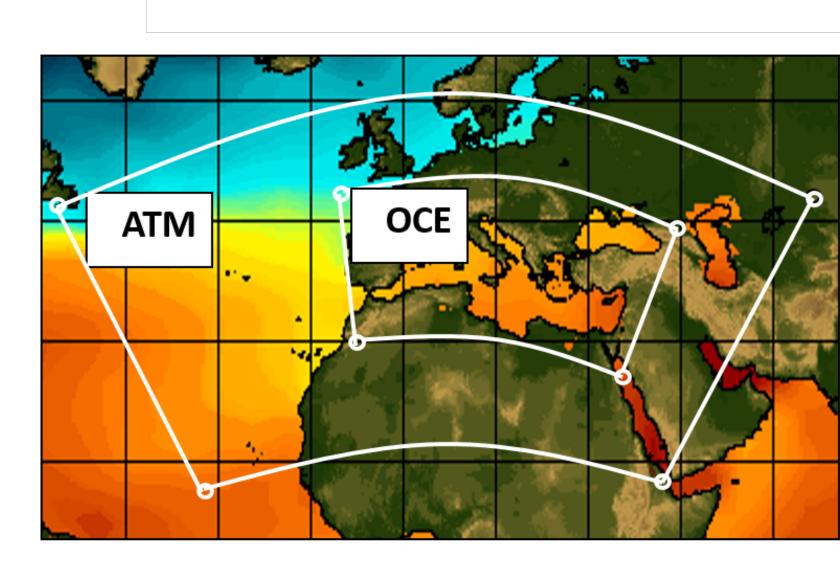
Coupled Data Assimilation in Navy ESPC

NRL Atmospheric Dynamics and Prediction²: Sergey Frolov, Craig H. Bishop, and Benjamin C. Ruston Vencore²: Peter L. Spence, Ole Martin Smedstad

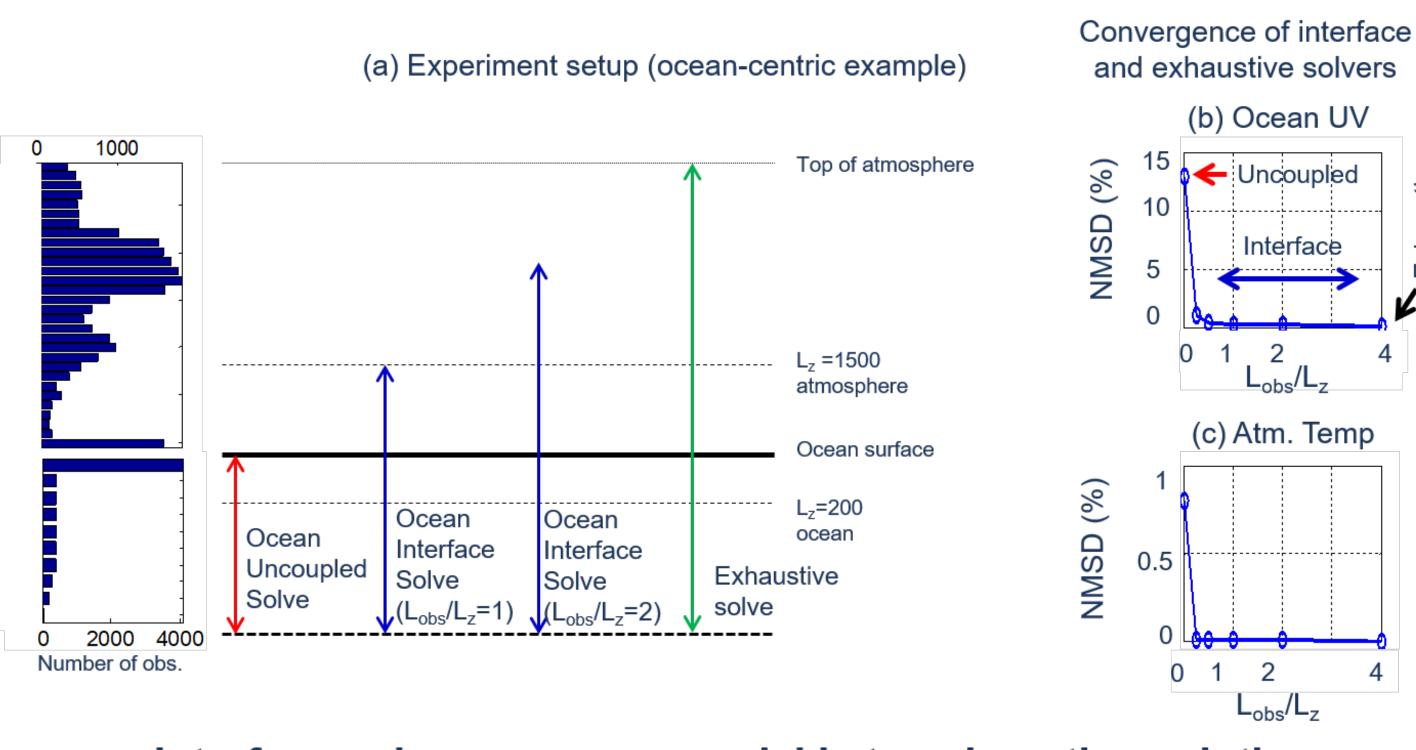
¹Naval Research Laboratory, Code 7320, Stennis Space Center, MS²Naval Research Laboratory, Code 7530, Monterey, CA³Vencore, Stennis Space Center, MS

- et.al. 2016) to implement
- Incremental development
- Coupled covariances will

Does interface solver work?

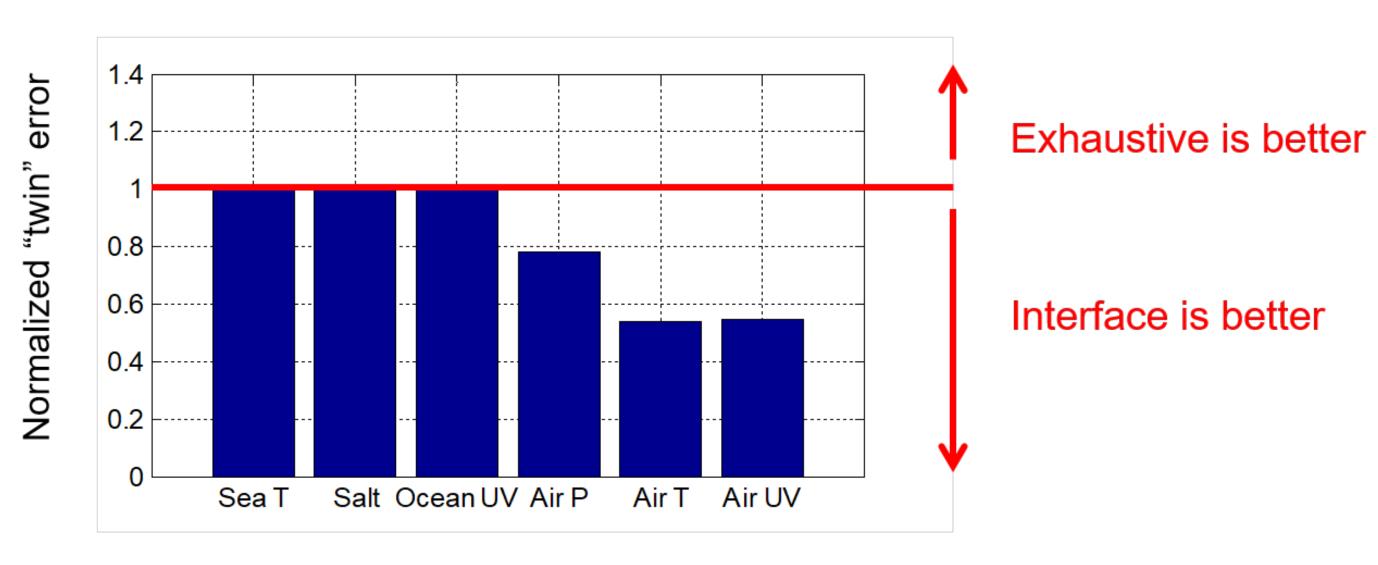


Does interface solver work?



Interface solver converges quickly to exhaustive solution

Interface solver can outperform exhaustive solver



| Solver configuration | Optimal ocean scales | Optimal atmospheric scales |
|--------------------------------|-------------------------|----------------------------------|
| Exhaustive | L =300 km | L = 500 km |
| Ocean + atm. bnd. layer | L = 300 km | L = 400 km |
| Atmosphere + ocean. bnd. layer | L = 500 km | L = 900 km |

Interface configuration



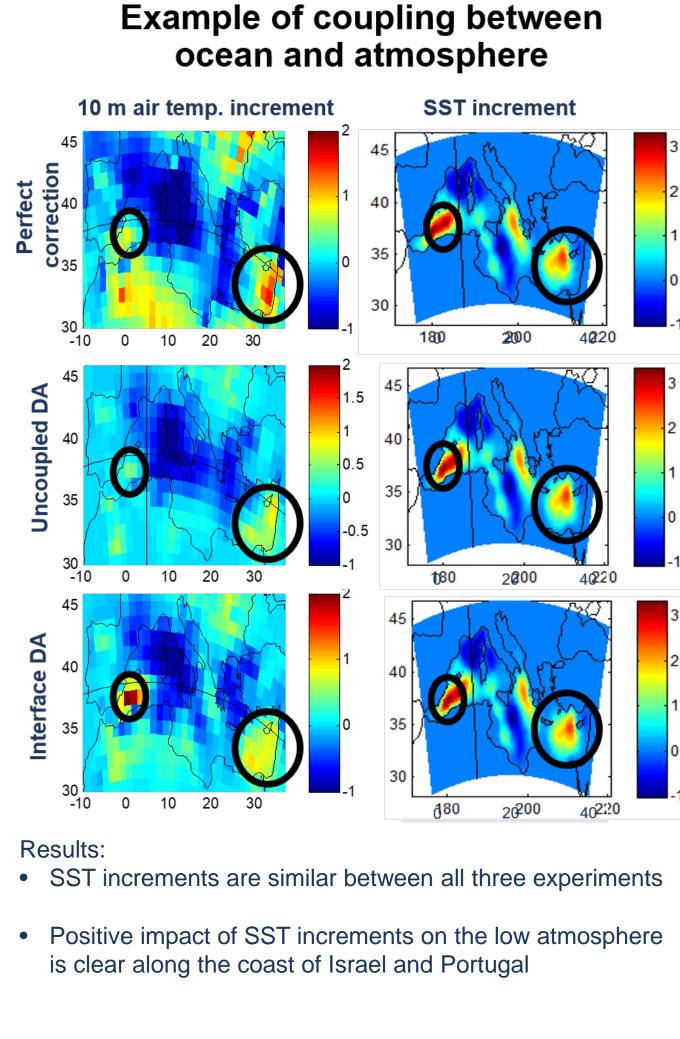
This work is supported by the Oceanographer of the Navy through the Office of Naval Research under program element 0603207N, funding document N0001417WX00491

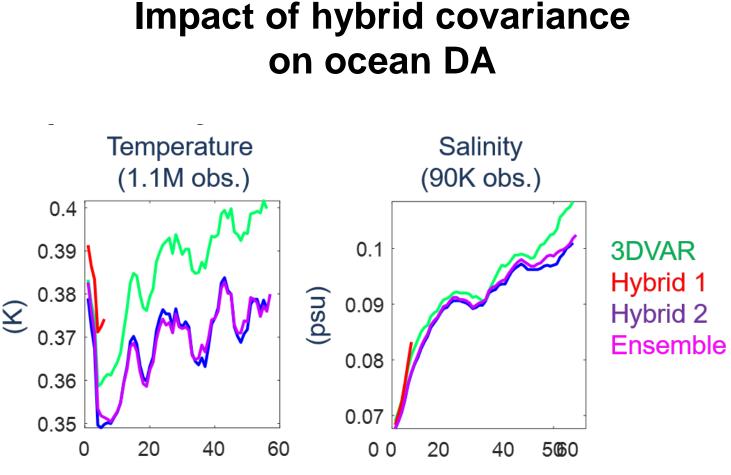
NRL Ocean Dynamics and Prediction¹: Charlie N. Barron, Clark D. Rowley, Tamara L. Townsend, Mozheng Wei, Max Yaremchuk, and Jan M. Dastugue

Forward model:

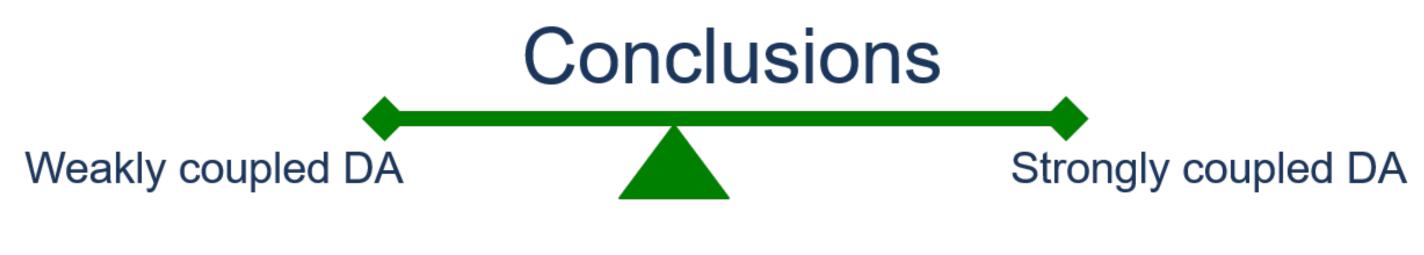
- Coupled, nested COAMPS/NCOM
- Atm. resolution 42 km
- Oce. resolution 12 km
- Coupling every 6 min.
- **Ensemble system:**
- 20 members
- Driven by global atm. ensemble
- Augmented by ET cycling
- **Observations:**
- Twin experiment based on real obs. locations
- DA system:
- Hybrid-3DVAR







Using hybrid covariances ocean DA in the Pacific reduces RMS 24-hour forecast errors relative to in situ temperature and salinity observations



Working hypothesis:

Specific work plans:

- atmosphere

A21F-2213

AGU Fall Meeting New Orleans, LA 11-15 December 2017

Surface salinity correction EnVar

Surface velocity correction EnVa

Results

Surface salinity correction 3DVAR

Surface velocity correction 3DVAR

EnVar solver with 20 perturbed-obs. members

Snapshot of the analysis increment over the equatorial Pacific

Ensemble (and hybrid, not shown) show more realistic-looking corrections to the salinity and velocity fields than the when using static covariances in standard 3DVAR

on atmosphere DA

Comparisons of static and ensemble increments

| Sensor | Channels | % Bias Reduction in the first guess |
|--------|-------------|--|
| IASI | water vapor | 42.0 |
| CRIS | water vapor | 1.3 |
| CRIS | surface | 24.3 |
| CRIS | troposphere | 22.2 |
| MHS | water vapor | 19.3 |
| ATMS | water vapor | 4.7 |
| GEOCSR | all | 2.2 |

Coupled DA reduces 6-hour forecast bias across a wide range of remote sensors sensitive to the lower atmosphere

Need to find right balance in coupled DA (e.g. outer loop coupling, interface solver)

• The forecast skill will degrade if we implement strongly-coupled DA right now (due to poor knowledge of the coupled error covariance). Over the next 10 years, implementing approximations to the stronglycoupled DA will allow refining the coupled error covariance and, at the same time, controlling the strength of the coupling.

Planned activities in the next year

Completing work on SST-sensitive channels

Tuning the performance of the ocean Hybrid-EnVAR

Implementing impact of ice velocities and temperatures on the

 Implementing impact of scatterometer winds, surface temperature, and humidity retrievals on the ocean

Impact of interface coupling

| Sensor | Channels | % Bias Reduction in the first guess |
|--------|-------------|--|
| ASI | water vapor | 42.0 |
| RIS | water vapor | 1.3 |
| RIS | surface | 24.3 |
| RIS | troposphere | 22.2 |
| /IHS | water vapor | 19.3 |
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| SEOCSR | all | 2.2 |
| | | |